ENGR-356
HW\# 5 - due at the start of lab (the day you have lab)
Because an op-amp has very high gain it can be used to compare two voltages. If one input (typically the inverting input) of the op-amp is connected to a known voltage (call this $\mathrm{V}_{1}$ or the reference voltage), the other input $\mathrm{V}_{2}$ is connected to a voltage that is changing, and there is no feedback, then as voltage $V_{2}$ becomes greater than $V_{1}$ by a small amount the output voltage will swing to a maximum (saturated) output voltage. If $V_{2}$ decreases and becomes less than $V_{1}$ by a small amount the output voltage will swing to a maximum (saturated) output voltage of the opposite polarity. Effectively the op-amp output is binary indicating if the unknown voltage is greater than or less than the reference voltage.

A potential problem can occur if the unknown voltage changes magnitude slowly as it approaches the reference voltage. If there is a little bit of noise on the unknown voltage the output may switch polarity back and forth as the noise voltage goes up/down.

To fix this switching problem positive feedback can be used. With positive feedback, as the unknown voltage $V_{2}$ reaches the reference voltage $V_{1}$ the op-amp output begins to change potential in the same direction as input $\mathrm{V}_{2}$. With positive feedback the changing output voltage thus adds to the $V_{2}$ input voltage causing it to continue changing in the same direction.


A consequence of the positive feedback is that the $V_{2}$ voltage at which switching takes place changes from being nearly equal to reference $V_{1}$ to being equal to $V_{1}$ plus or minus some amount. This "some amount" is determined by a voltage divider relationship, i.e. Vout $x(R 1 /(R 1+R 2)$ ). And thus for an increasing $\mathrm{V}_{2}$ voltage the op-amp output will switch at a different value of $\mathrm{V}_{2}$ than for a decreasing $\mathrm{V}_{2}$ input. This is called hysteresis.

Assuming op-amp input current is zero (ideal) the only path for current to flow is through R1 and R2. Also, because we have positive feedback rather than negative feedback we cannot say that the voltage at $V_{x}$ is always zero or even close to zero. The voltage at $V_{x}$ will change proportional to $V_{2}$ input. But Op-amp output will still change polarity when $V_{x}$ becomes equal to $V_{1}$ which is zero in this circuit.

## Example

Assume R 1 is 10 k ohms, R 2 is 1 meg ohm, $\mathrm{V}_{2}$ is zero volts, and that at present the op-amp output is saturated in the negative direction, i.e. -10 volts. What is the voltage at $V_{x}$ ?

$$
V_{x}=\operatorname{Vout} x(R 1 /(R 2+R 1))=(-10) \times(10 k /(1 \mathrm{meg}+10 k))=-0.099 \text { volts }
$$

## Problems to solve

Assume that the op-amp output saturates at $+/-10$ volts (i.e. the power supply voltages).

1) Find reasonable values for R1 and R2 such that the op-amp will switch when $V_{2}=+1.0$ volts and when $V_{2}=-1.0$ volts.
2) Figure 2.26 in the text shows the Miller integrator circuit topology and on that page notes that the transfer function for this topology is that of a Single Time Constant (STC) network. Thus the Miller integrator topology can be used as a first order low-pass filter whose magnitude and phase response is that shown in figure 1.23 of the text.. On page 1016 of the text is example 14.2 that illustrates using this circuit topology to implement a first order low-pass filter. Note in figure 1.23 (a) there is a frequency labeled 1 where the magnitude is 3 db less than at a frequency of 0.1 or less (on this diagram the frequencies have been normalized to one). When discussing filters we call this frequency the cut-off frequency where signal magnitude passing through the filter is reduced by 3 db , i.e. is 0.707 times that at low frequency (this frequency in radians is the pole-frequency omega zero). Note that at frequencies above cut-off, signal magnitude coming out of the filter become less and less as frequency goes up. Hence the title low-pass. At very high frequency there should be nearly zero signal coming out.

Follow example 14.2 to design a low-pass filter whose cut-off frequency (omega zero) is 2000 Hz and DC gain is $5 \mathrm{~V} / \mathrm{V}$. Use a 0.01 uF capacitance value.

