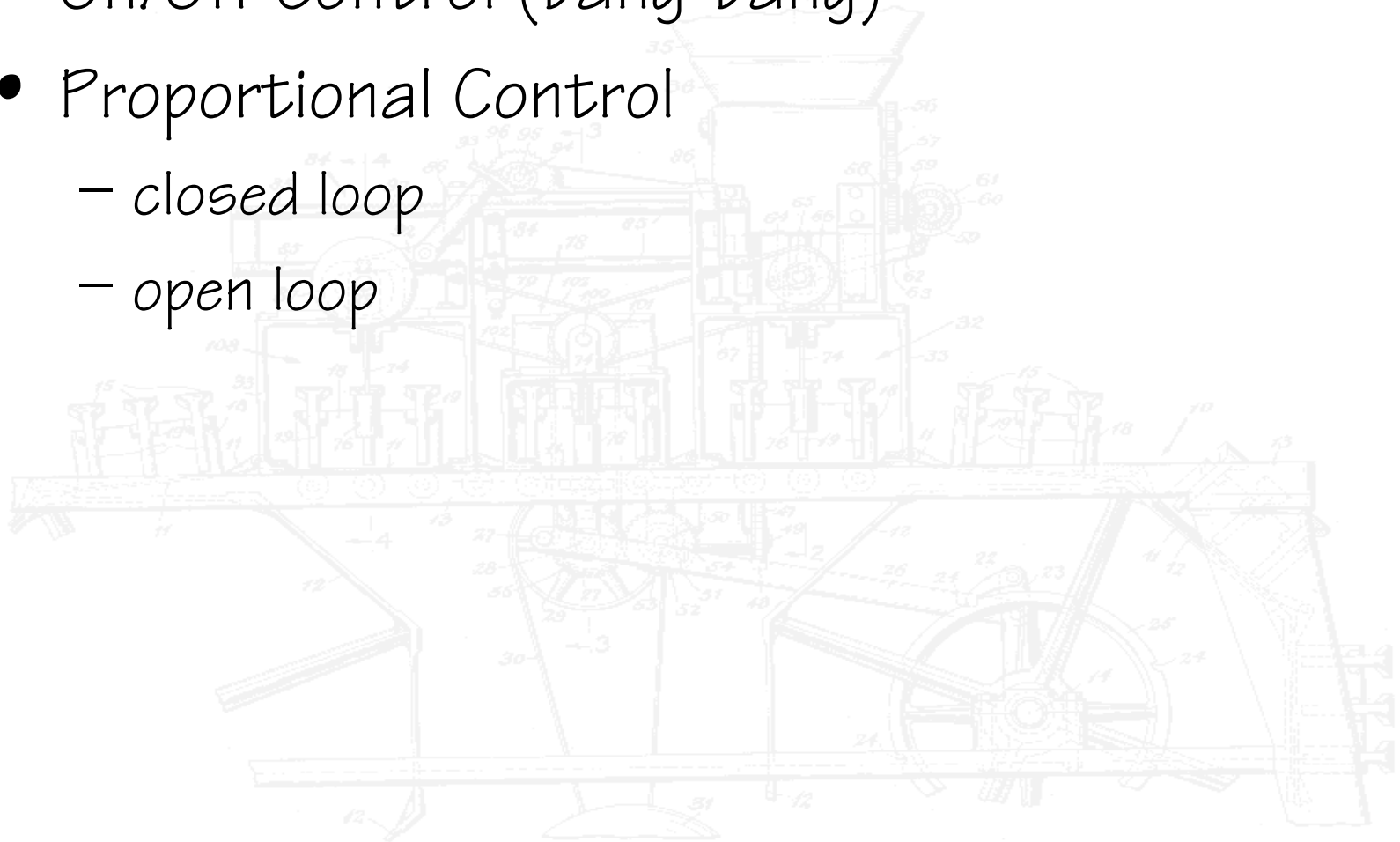


# CONTROL OF MOTION

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- On/Off Control (bang-bang)
- Proportional Control
  - closed loop
  - open loop



# DIGITAL LOGIC EXPRESSIONS

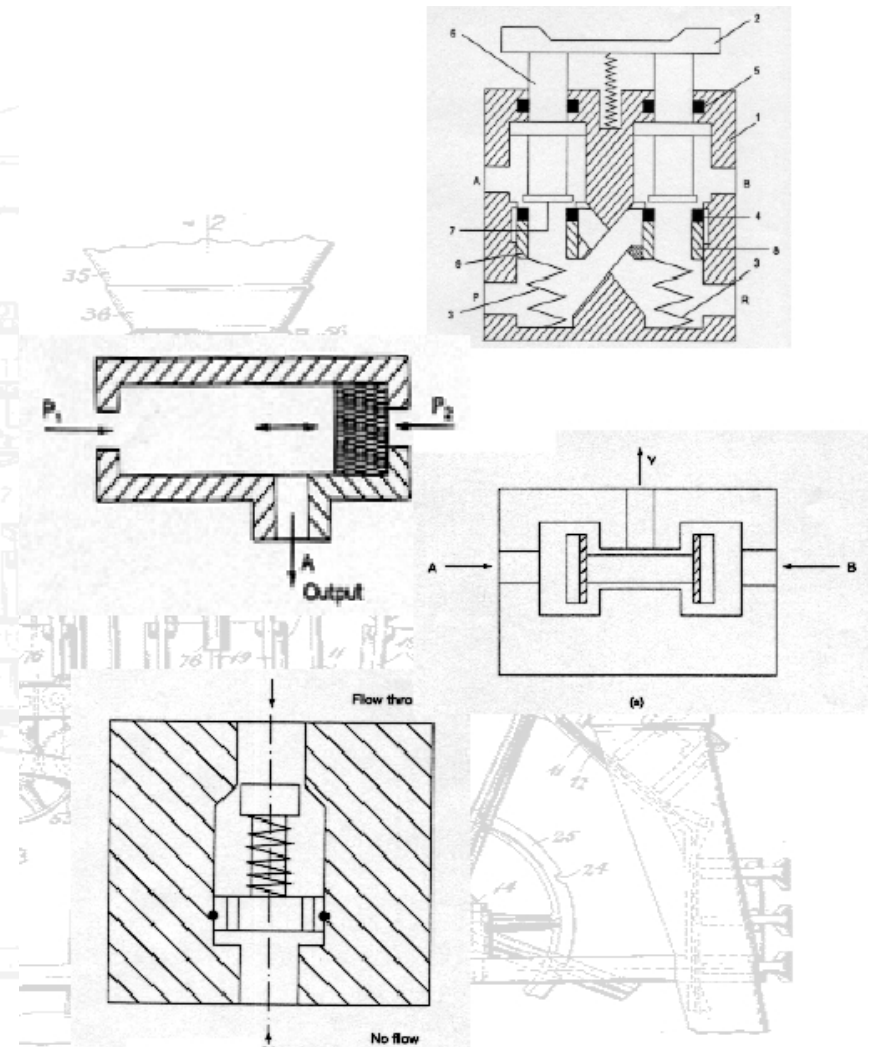
---

$$oPICK = (iPARTRDY \cdot iCYLRETRACT + oPICK \cdot /iCYLEXTEND) \cdot /iESTOP$$

- Pickup when part is ready, **and** cylinder is retracted, **and** emergency stop is **not** on, **or** while cylinder is not fully extended **and** emergency stop is **not** on.

# PNEUMATIC LOGIC ELEMENTS

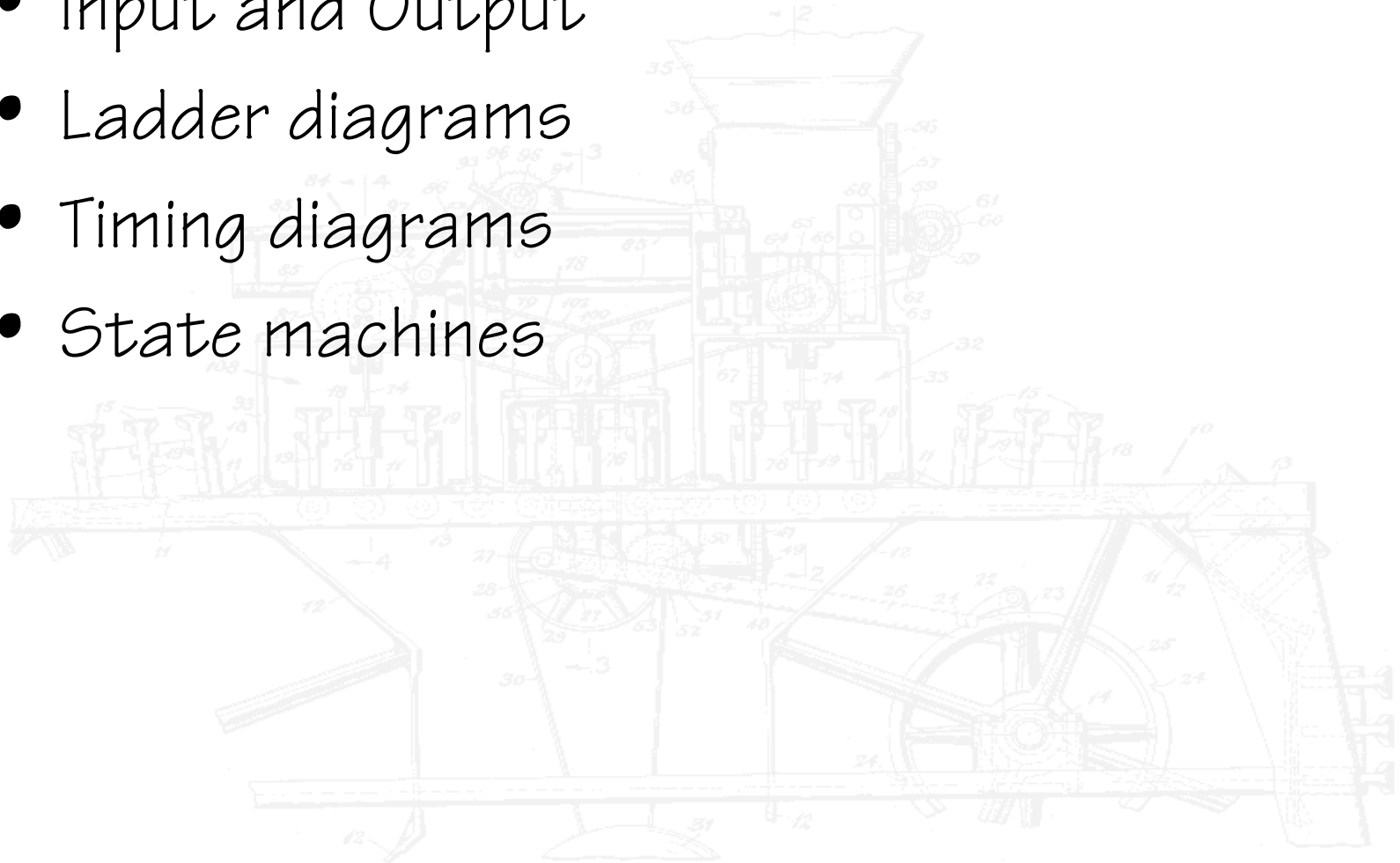
- Directional control valve
- Shuttle valve - OR function
- Twin pressure valve - AND function
- Other functions
  - Check valve
  - Speed control valve
  - Time delay valve



# ELECTRIC LOGIC CONTROL

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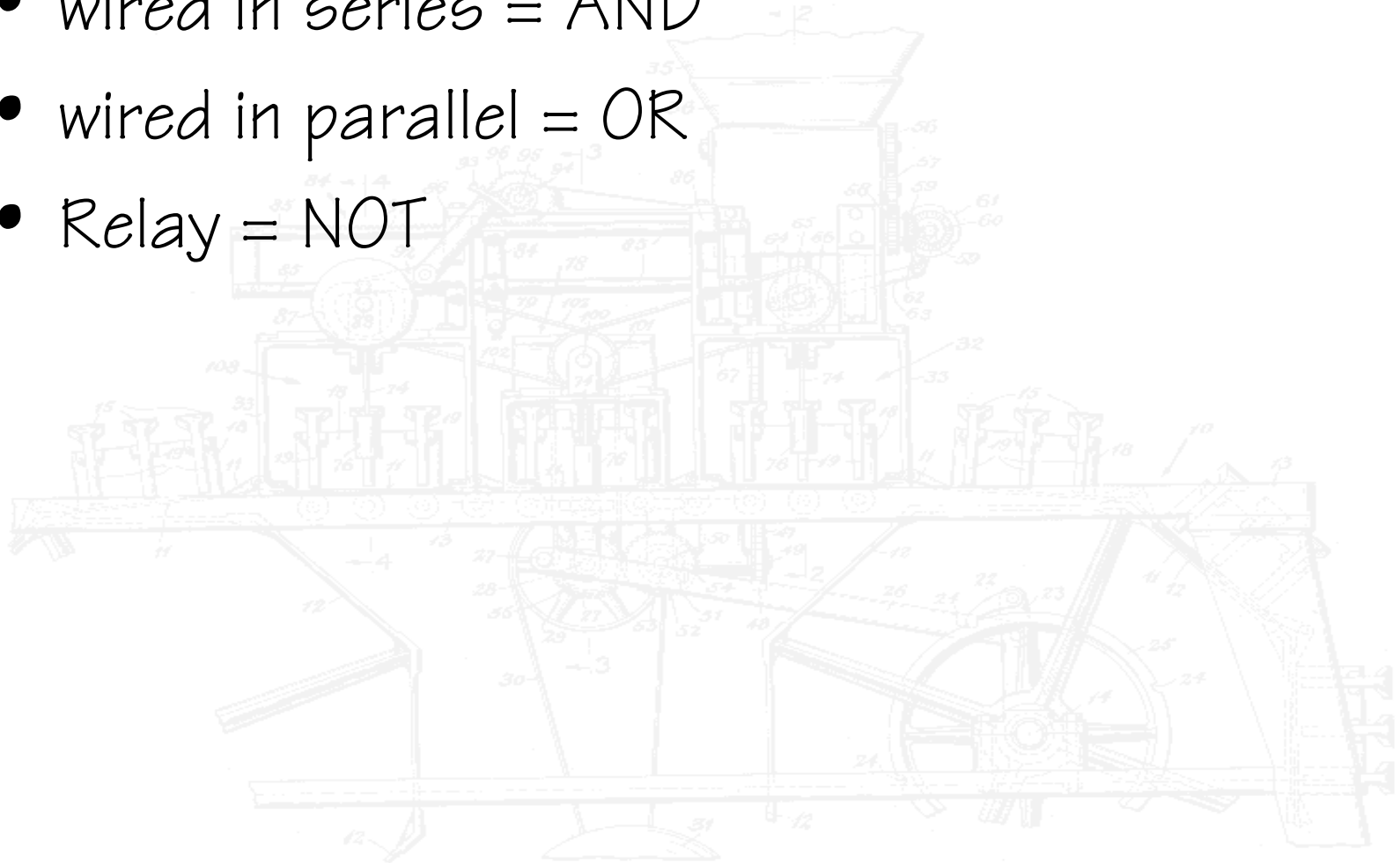
- Input and Output
- Ladder diagrams
- Timing diagrams
- State machines



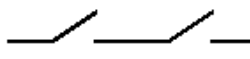
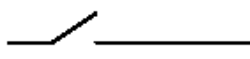
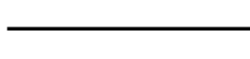


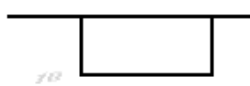
# ELECTRIC LOGIC ELEMENTS

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- wired in series = AND
- wired in parallel = OR
- Relay = NOT



# BOOLEAN ARITHMETIC

- 0 and 0 = 0 ( $0 \cdot 0 = 0$ ) 
- 0 and 1 = 0 ( $0 \cdot 1 = 0$ ) 
- 1 and 1 = 1 ( $1 \cdot 1 = 1$ ) 
- 0 or 0 = 0 ( $0 + 0 = 0$ ) 
- 0 or 1 = 1 ( $0 + 1 = 1$ ) 
- 1 or 1 = 1 ( $1 + 1 = 1$ ) 
- not 0 = 1 ( $/0 = 1$ )

---

$$A + /A = 1$$

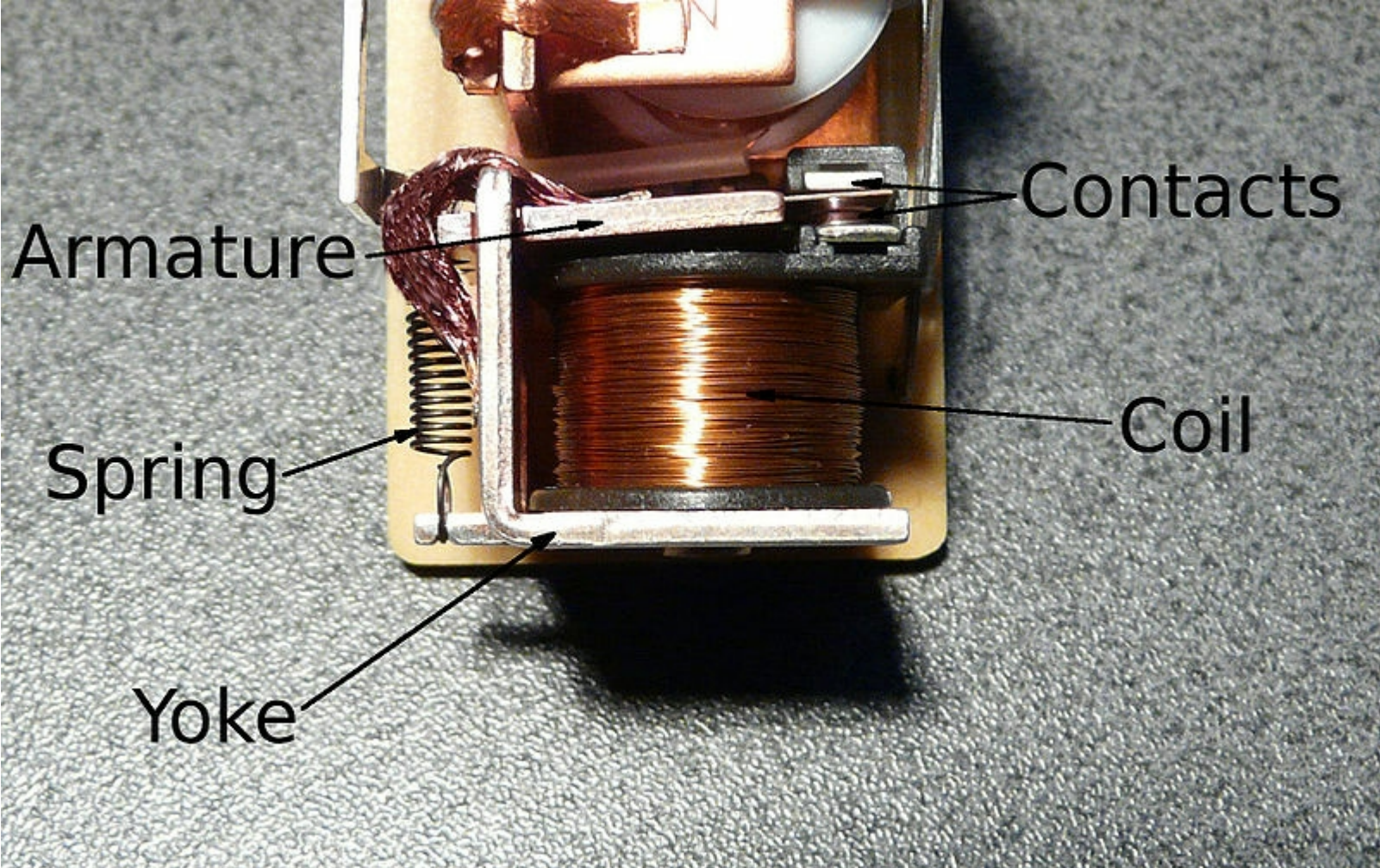
$$A \cdot B = B \cdot A$$

$$A \cdot B + A \cdot C = A \cdot (B+C)$$



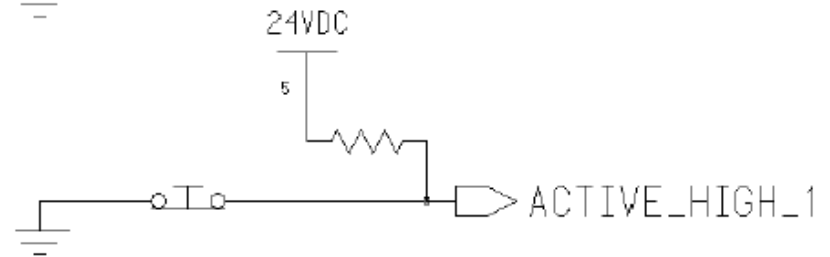
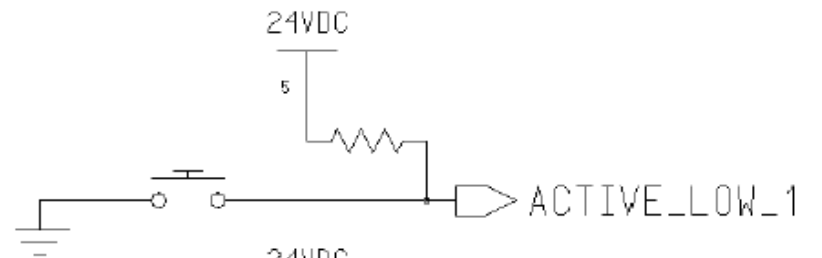
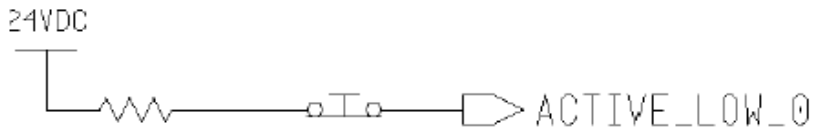
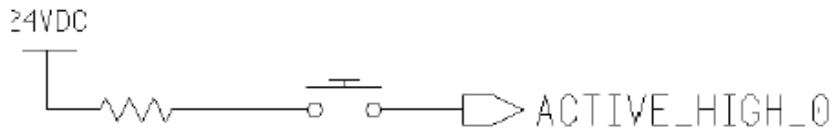
# RELAYS

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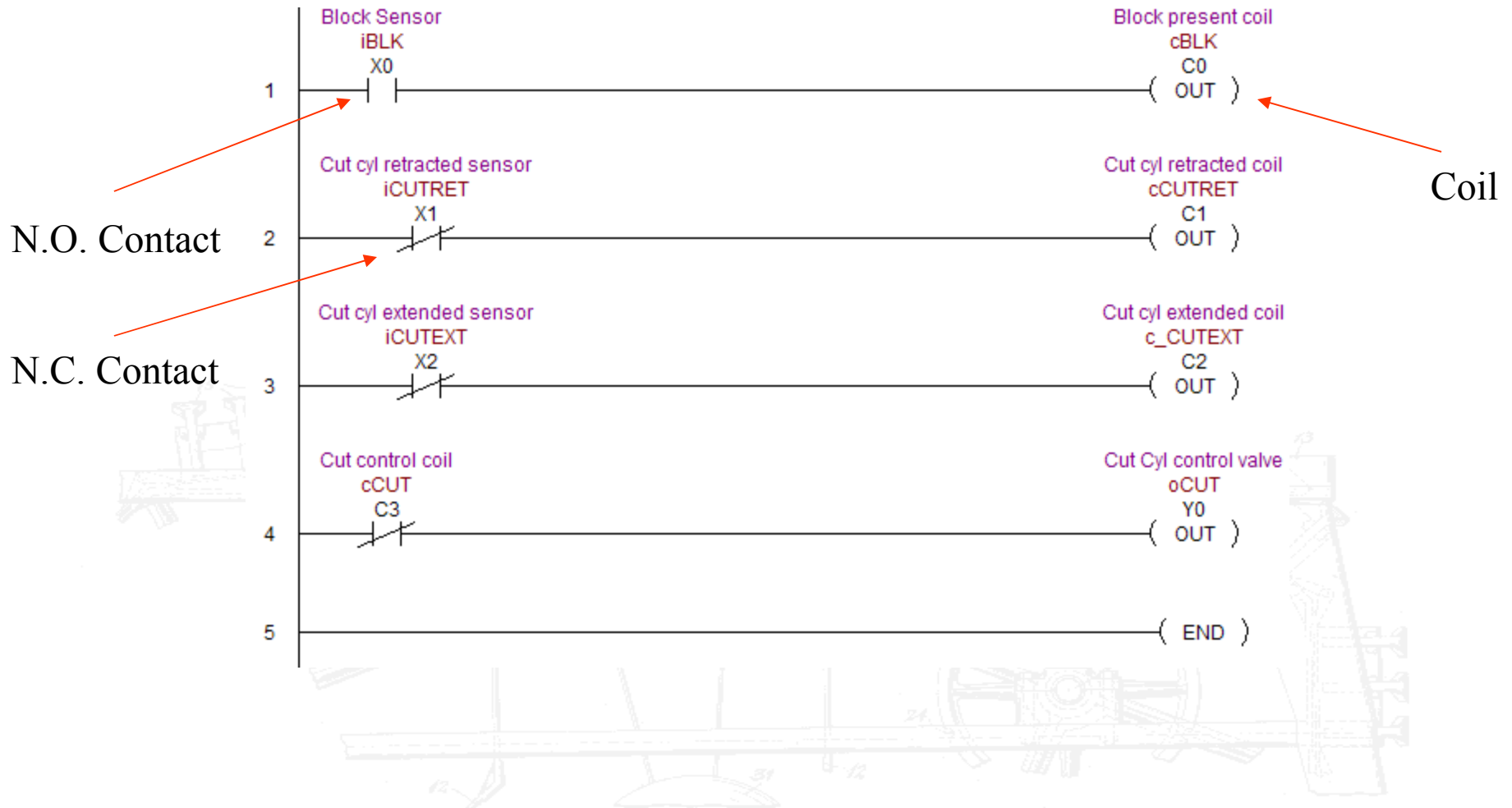
# I/O ACTIVITY LEVELS

- Active = TRUE Inactive = FALSE
- Active High - **active** level is +24 volts
- Active Low - **active** level is 0 volts (GND)

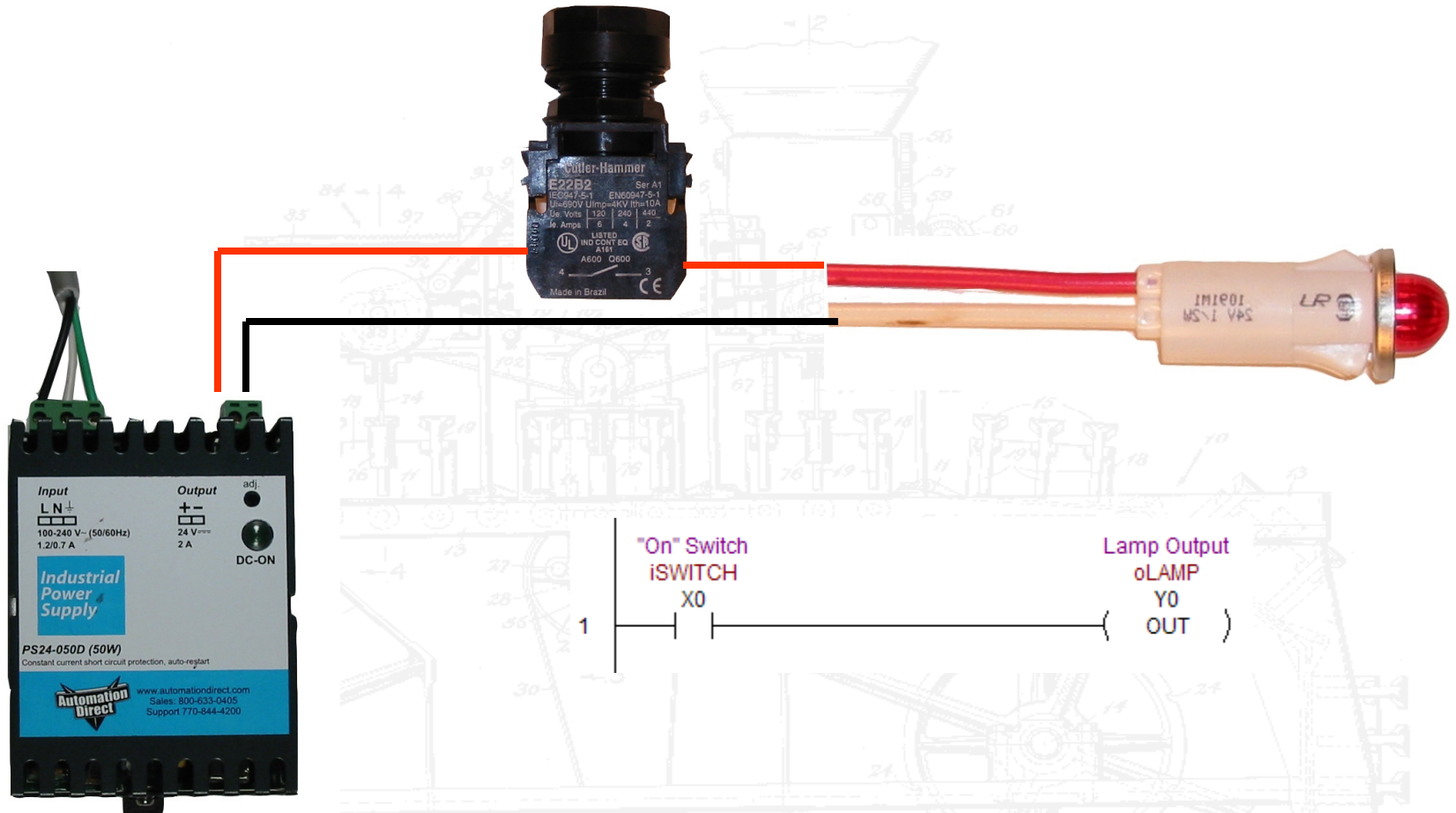




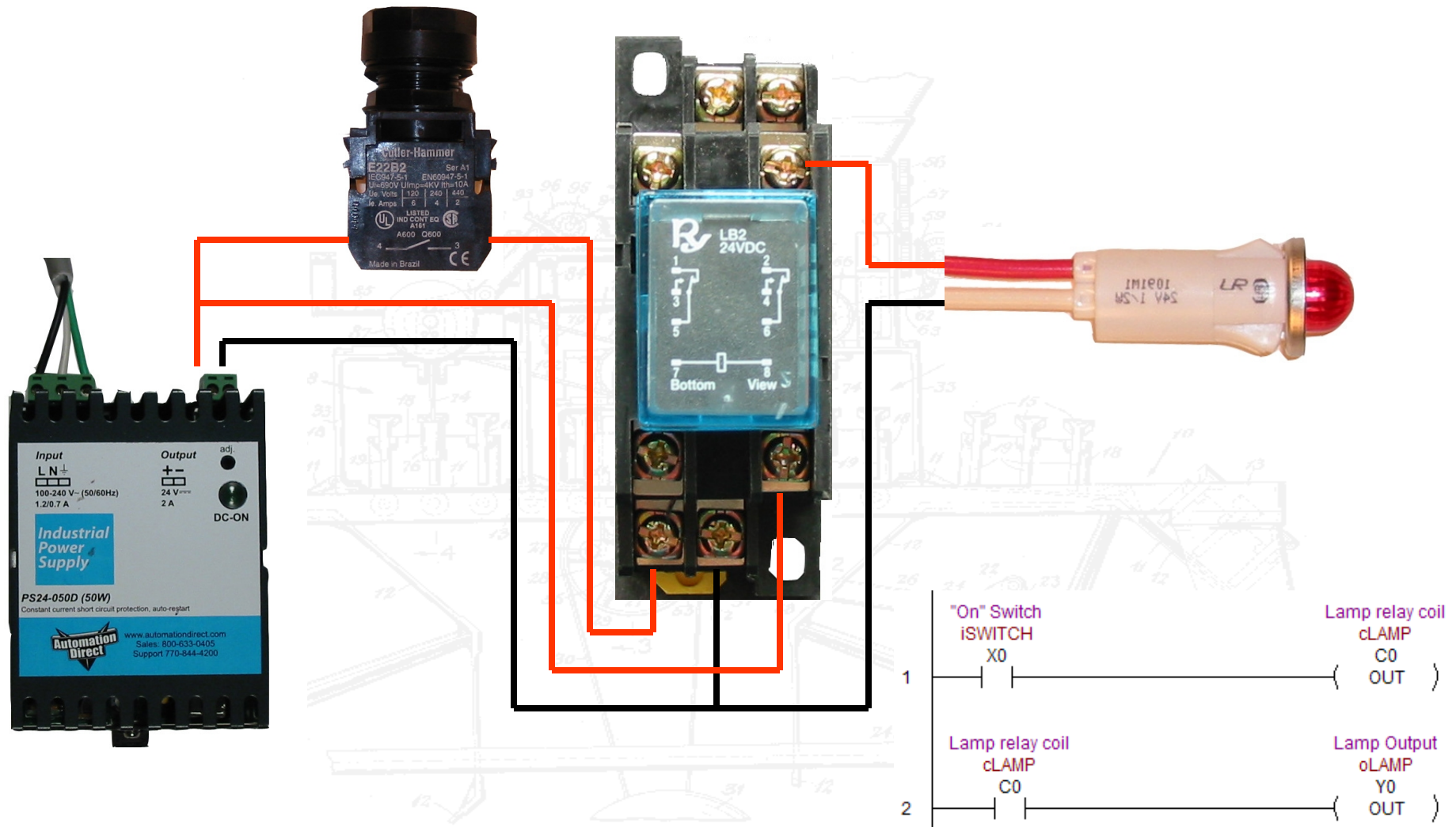
# LADDER DIAGRAMS



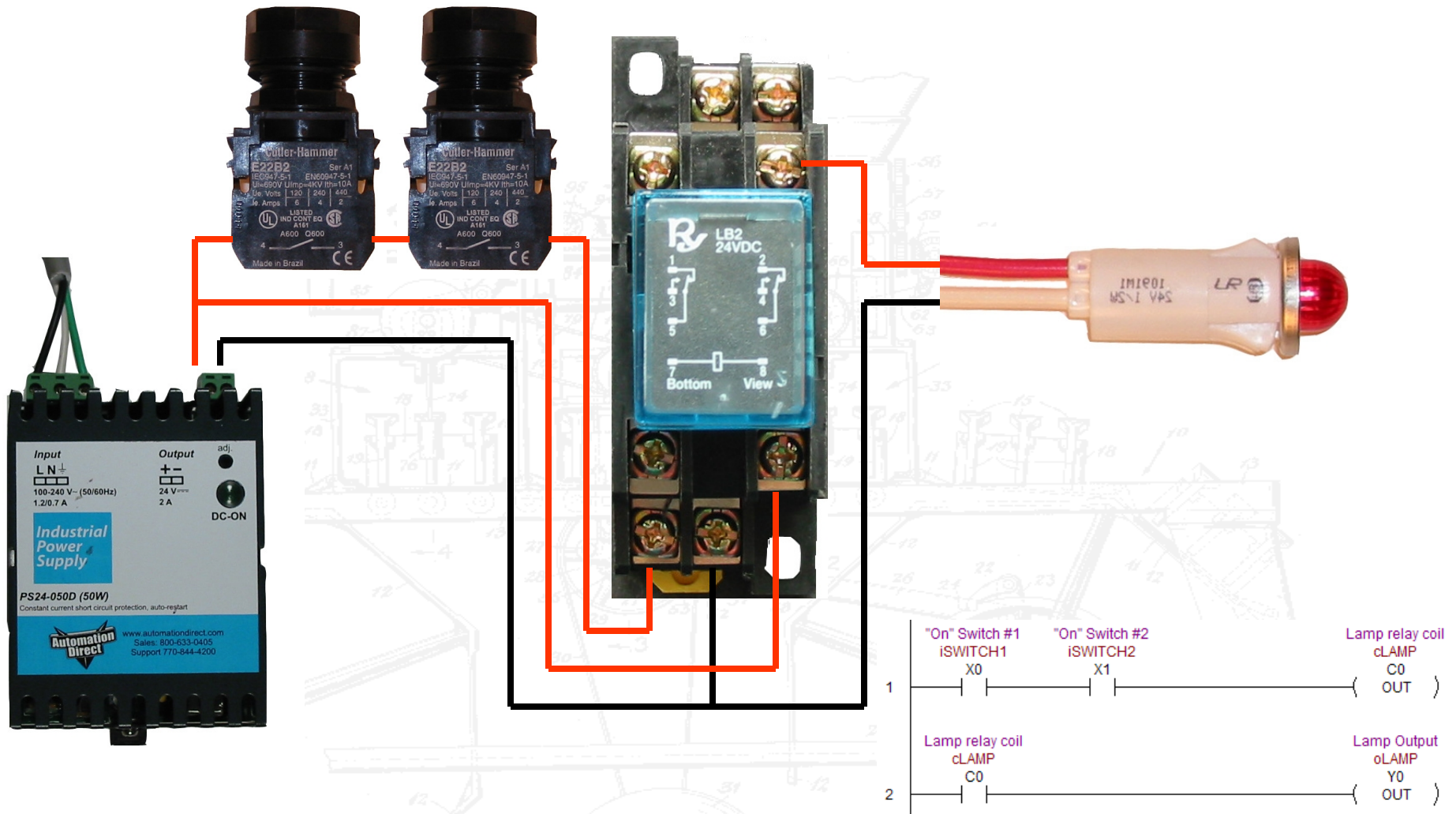
# EXAMPLE – LIGHT SWITCH



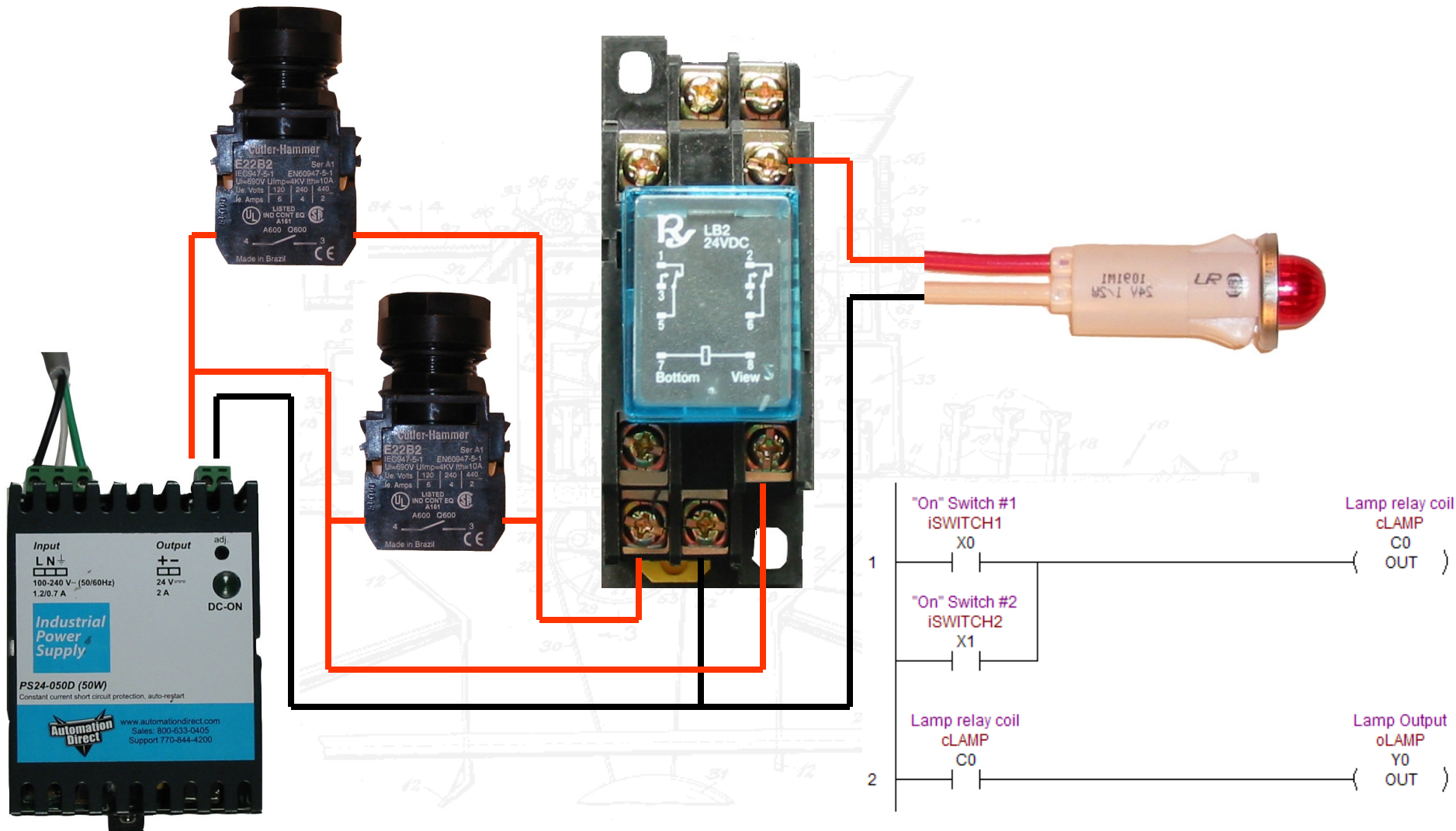
# EXAMPLE – LIGHT RELAY



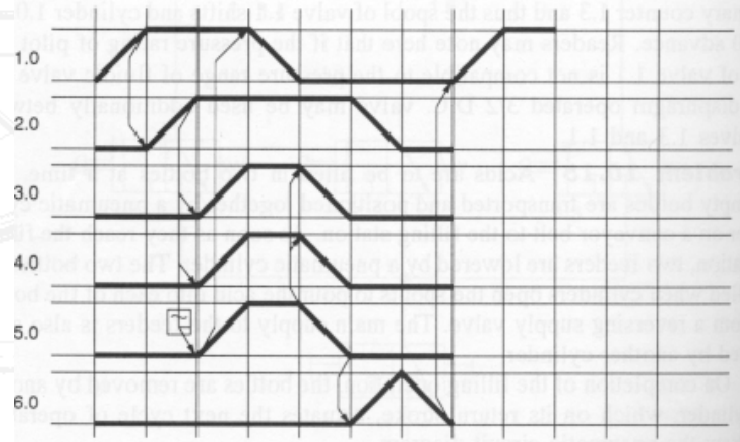
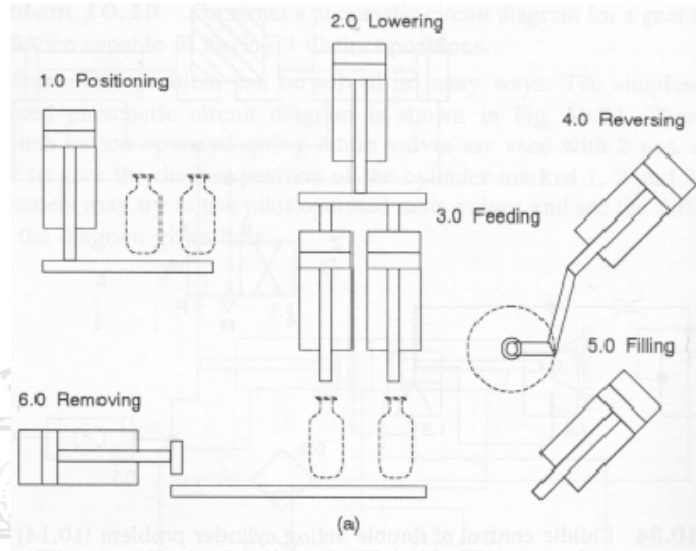
# EXAMPLE – LIGHT RELAY, “AND” LOGIC



# EXAMPLE – LIGHT RELAY – “OR” LOGIC

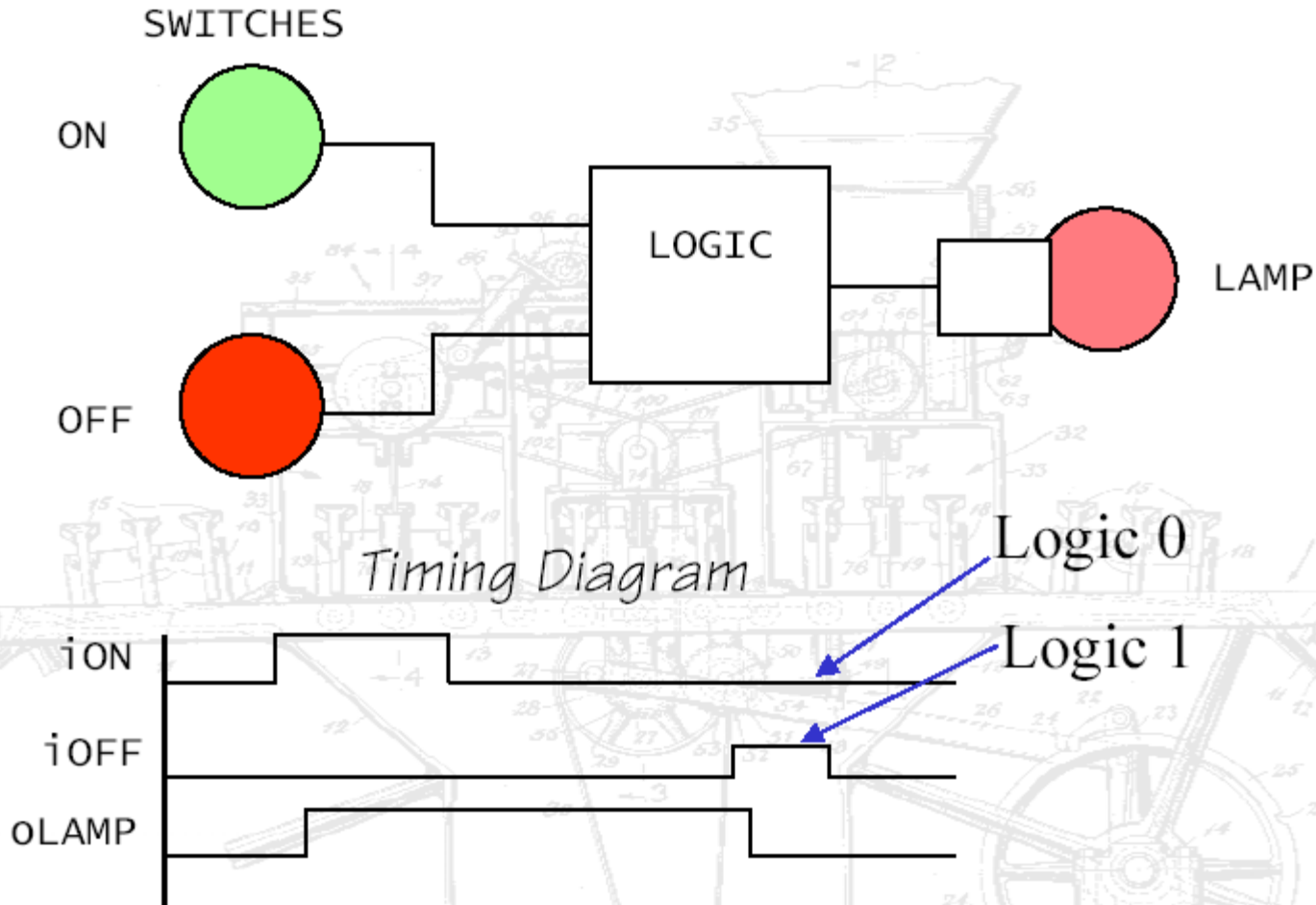


# TIMING DIAGRAMS



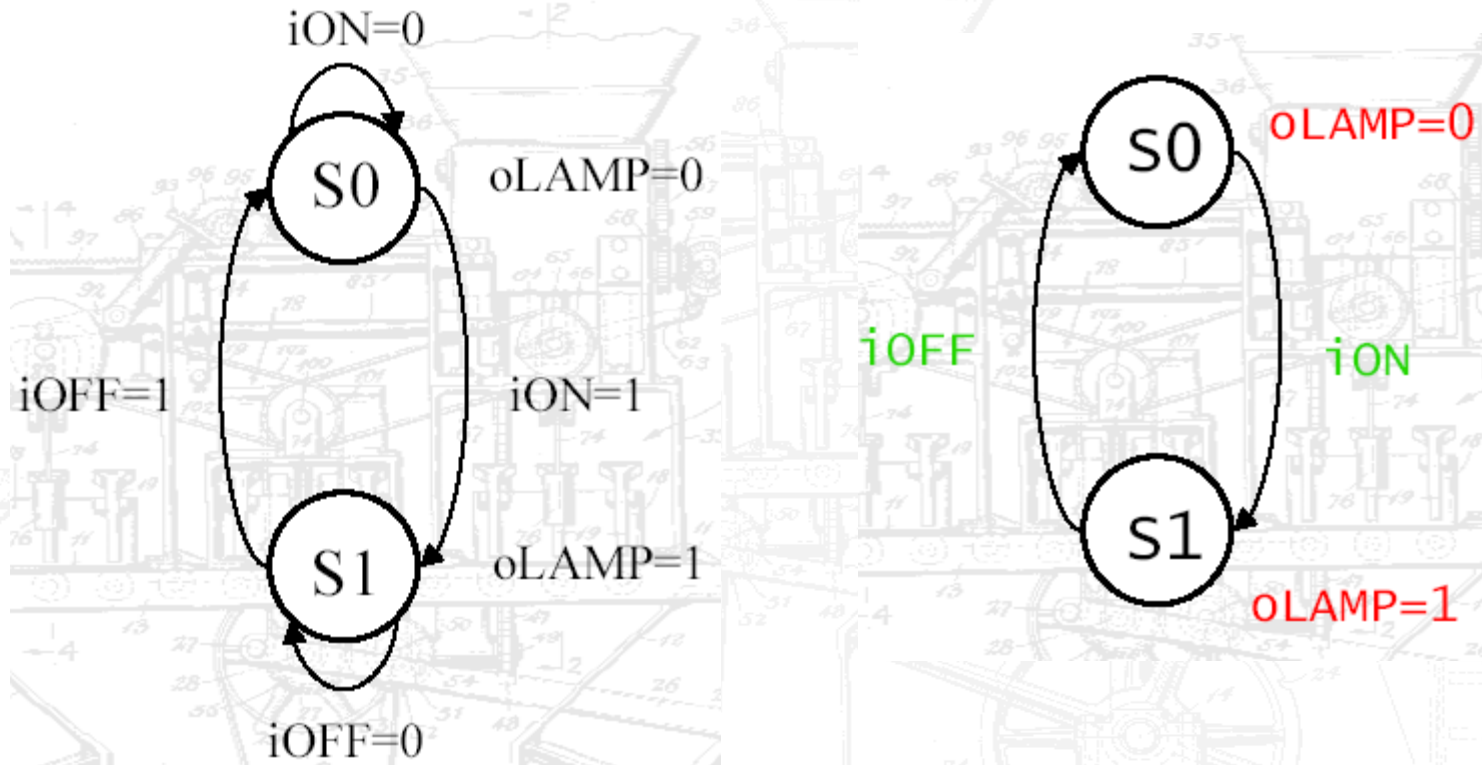


# STATE MACHINES



# STATE DIAGRAM

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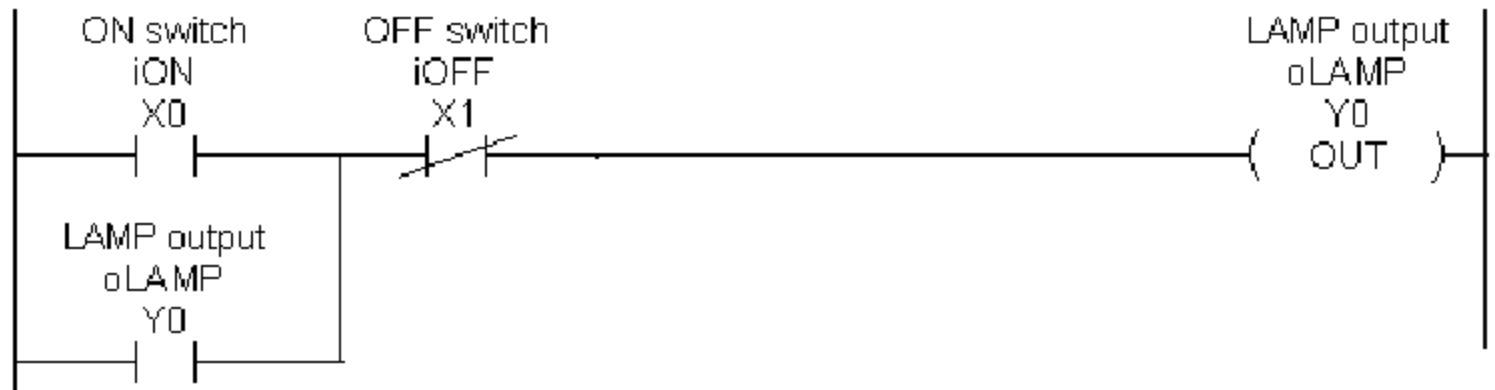


# LOGIC EQUATION AND LADDER DIAGRAM

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$$oLAMP = /iOFF \cdot (iON + oLAMP)$$

24VDC



# EXAMPLE – LATCHING RELAY LOGIC

