

- 1) Analyzing the product and the process
 - a) production scale
 - b) adding value
 - c) how would you make this by hand?
 - d) what is your required production rate?
 - e) part tolerances
- 2) Documentation
 - a) Memos
 - b) Reports
 - c) Drawings & part lists
- 3) Feeding & Fabrication
 - a) Material removal
 - i) CNC
 - ii) Rotating work
 - (1) lathe
 - (2) turning center
 - iii) Rotating tool
 - (1) vertical mill
 - (2) horizontal mill
 - (3) machining center
 - (4) clamping and fixturing
 - iv) Feeds & Speeds
 - v) Automatic screw machines
 - vi) Centerless grinding
 - b) Forming
 - i) sheet metal
 - (1) folding
 - (2) punching
 - (3) shearing
 - ii) extruding
 - iii) sintering
 - iv) molding and casting
 - c) Joining
 - i) Rivets
 - ii) press-fit fasteners
 - iii) Threaded fasteners
 - iv) Snap fastening
 - v) Adhesives
 - vi) Welding
 - d) Feeding parts
 - i) orientation and symmetries
 - ii) conveyors
 - iii) vibratory feed bowls
 - iv) pick & place
- 4) Generating motion
 - a) linear motion
 - i) pneumatic cylinders
 - ii) electric solenoids
 - iii) vibratory systems
 - b) rotary motion
 - i) DC motors

- ii) AC motors
 - (1) stepper
 - (2) brushless
 - (3) induction
- c) conversion between rotary and linear
 - i) lead screws
 - ii) rack & pinion
 - iii) four-bar linkages
- 5) Control of motion
 - a) On/off control
 - i) pneumatic logic
 - ii) electric controls
 - (1) relays
 - (2) programmable logic controllers (PLC)
 - (a) digital logic
 - (b) ladder diagrams
 - (c) timing diagrams
 - (d) state machines
 - (i) state diagrams
 - (ii) state transition tables
 - (iii) state logic equations
 - (iv) RLL-Plus stage programming
 - (e) input and output
 - (i) DC
 - 1. sinking
 - 2. sourcing
 - (ii) AC
 - (f) higher level functions
 - (i) timers
 - (ii) counters
 - (iii) math
 - (3) position sensing
 - (a) mechanical
 - (b) optical
 - (i) modulated/non-modulated
 - (ii) reflective/transmissive
 - (iii) light on/dark on
 - (iv) fiber optic
 - (c) magnetic
 - (i) reed switch
 - (ii) hall effect
 - (iii) inductive proximity
 - b) Proportional control
 - i) sensors
 - (1) resistive and bridges
 - (2) optical
 - (a) incremental
 - (b) absolute
 - (3) PLC highspeed I/O
 - (a) highspeed counter
 - (b) quadrature counter

- (c) stepper drive
 - (4) magnetostrictive
 - (5) 4-20mA interface
 - (6) PLC analog I/O
 - ii) PID controllers
 - (1) PLC PID control functions
 - (2) Basic control theory
 - (a) P,I,D control
 - (b) PI, PD, and PID composite control
 - (c) analog and pneumatic controllers
 - c) Factory communications
 - i) wiring
 - (1) noise sources
 - (a) common impedance coupling
 - (b) magnetic field coupling
 - (c) electric field coupling
 - (2) twisted-pair
 - (3) coax (and twin-ax)
 - (4) shielding and grounding
 - (5) transmission line theory
 - (a) reflections
 - (b) termination
 - ii) signalling
 - (1) RS-232
 - (2) RS-485
 - (3) Ethernet
 - iii) protocols
 - (1) master/slave vs. peer-to-peer
 - (2) deterministic vs. asynchronous
 - (3) examples
 - (a) TCP/IP
 - (b) DeviceNet
 - iv) PLC communications
 - d) Human/machine interface (HMI or MMI)
 - i) system control
 - ii) data acquisition
 - iii) analysis and display
 - iv) factory database
 - v) resource and work-in-process tracking
 - vi) statistical process control
 - vii) alarms and logging
- 6) Additional topics not really covered
 - a) Non-discrete manufacturing
 - i) web materials
 - ii) continuous flow processes
 - b) Efficiency and effectiveness
 - i) Just-In-Time
 - ii) Flexible manufacturing
 - c) Throughput and production rate
 - i) Jams & malfunctions
 - ii) buffers